Start to plan your RC car program. First, read the descriptions below.

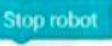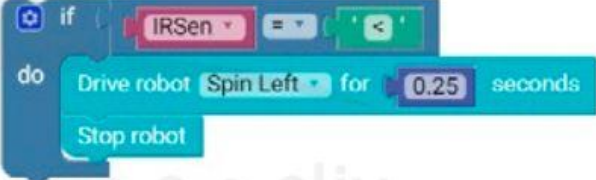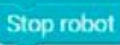Match the descriptions with the programming blocks.

Description		Programming blocks
Set the pins for servomotors.		if (IRSen ▾ = ▾ ' ^ ') do Drive robot Forward ▾
Set the pin for remote control and the IR sensor.		Configure drive robot: left motor pin# D3 ▾ , right motor pin# D6 ▾ Stop robot
Receive input using the IR sensor.		Configure remote control and IR sensor on pin# D12 ▾
Respond to user-initiated events to move forwards,		if (IRSen ▾ = ▾ ' < ') do Drive robot Spin Left ▾ for 0.25 seconds Stop robot
Respond to user-initiated events to move left,		set IRSen ▾ to (get IR value