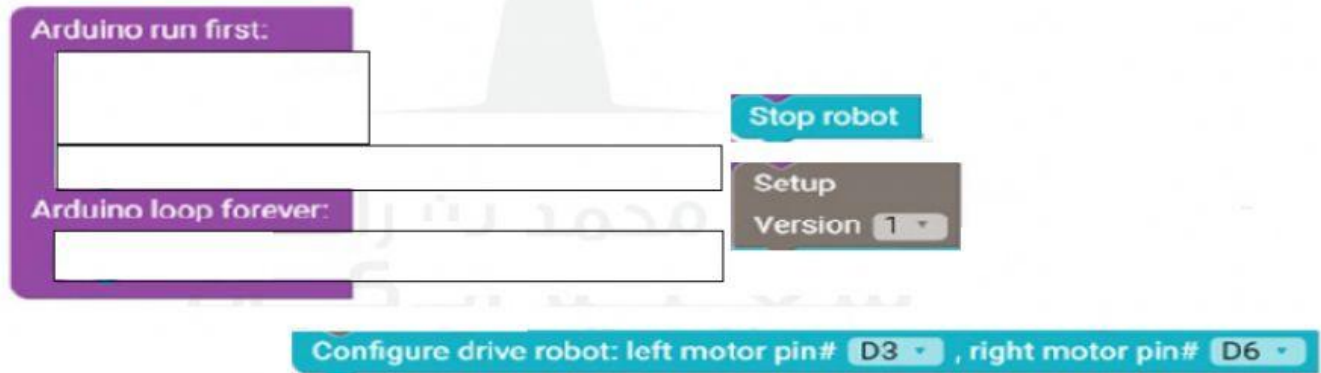


calibrate the servomotors:

- ⦿ connect the servomotors to pins 3 and 6.
- ⦿ create and upload a servomotor program with a stop command.
- ⦿ use a screwdriver to rotate the screw on the bottom of each servomotor until it stops moving.

Here is an example of a servomotor program with a stop instruction.



The image shows a Scratch-style Arduino code editor interface. On the left, there is a purple sidebar with two sections: "Arduino run first:" and "Arduino loop forever:". The "Arduino run first:" section contains a single empty text box. The "Arduino loop forever:" section contains a single empty text box. To the right of the code editor, there is a "Stop robot" button. Below the code editor, there is a "Setup" button and a "Version" dropdown menu set to "1". At the bottom, there is a "Configure drive robot:" bar with two dropdown menus: "left motor pin#" set to "D3" and "right motor pin#" set to "D6".

Arduino run first:

Arduino loop forever:

Stop robot

Setup

Version 1

Configure drive robot: left motor pin# D3 , right motor pin# D6