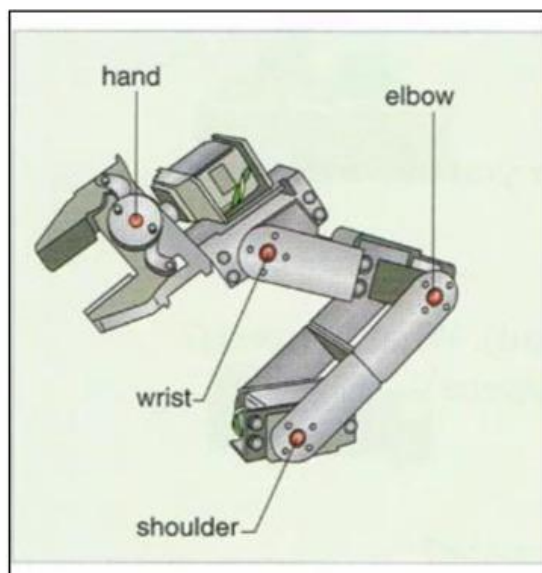


The robot arm



can (x6) can't has (x4) is (x3) isn't

This robot arm (1) _____ like a human arm. It (2) _____ a 'wrist', an 'elbow' and a 'shoulder'.

The 'wrist' (3) _____ like the human wrist. It (4) _____ three movements. It (5) _____ rotate. It (6) _____ move from side to side. It (7) _____ move up and down.

The 'elbow' (8) _____ like the human elbow. It (9) _____ one movement. It (10) _____ move up and down.

The 'shoulder' (11) _____ like the human shoulder, because it only (12) _____ two movements. It (13) _____ rotate, and it (14) _____ move up and down. But it (15) _____ move sideways.