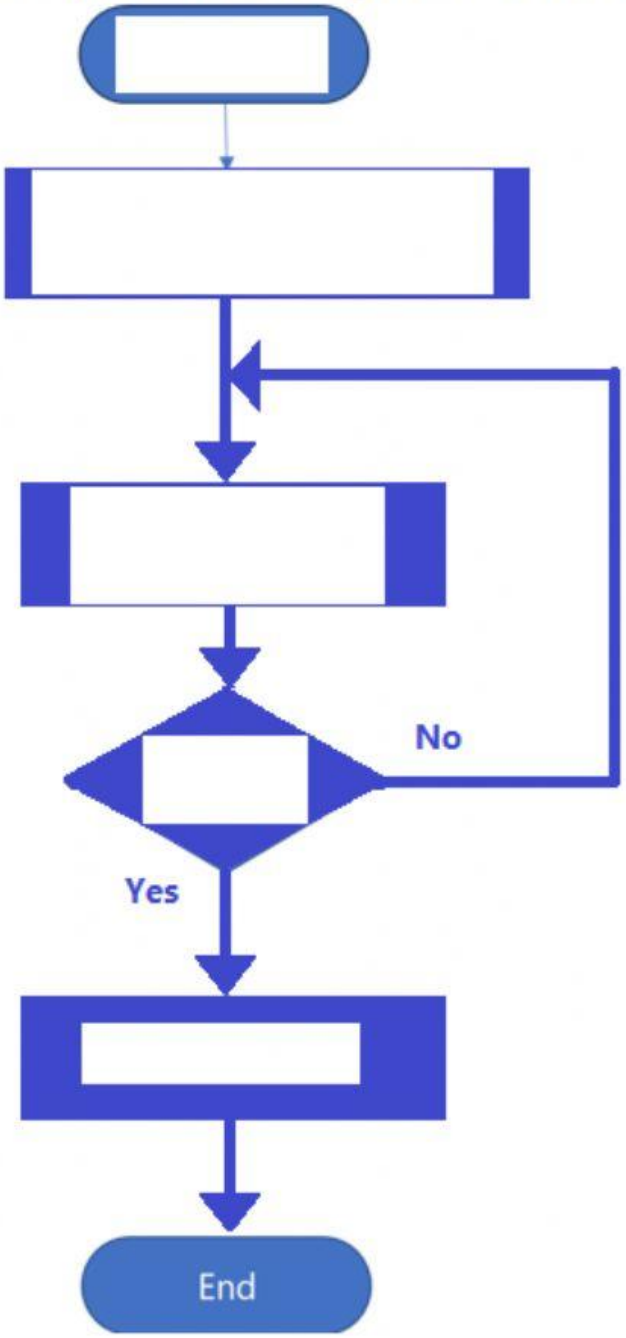
Create a simple flowchart algorithm to move a robot from point A to point B.



Set the pins connected to the servomotors.

Start

Move the robot forwards

Stop the Robot

is point B reached?

LIVEWORKSHEETS