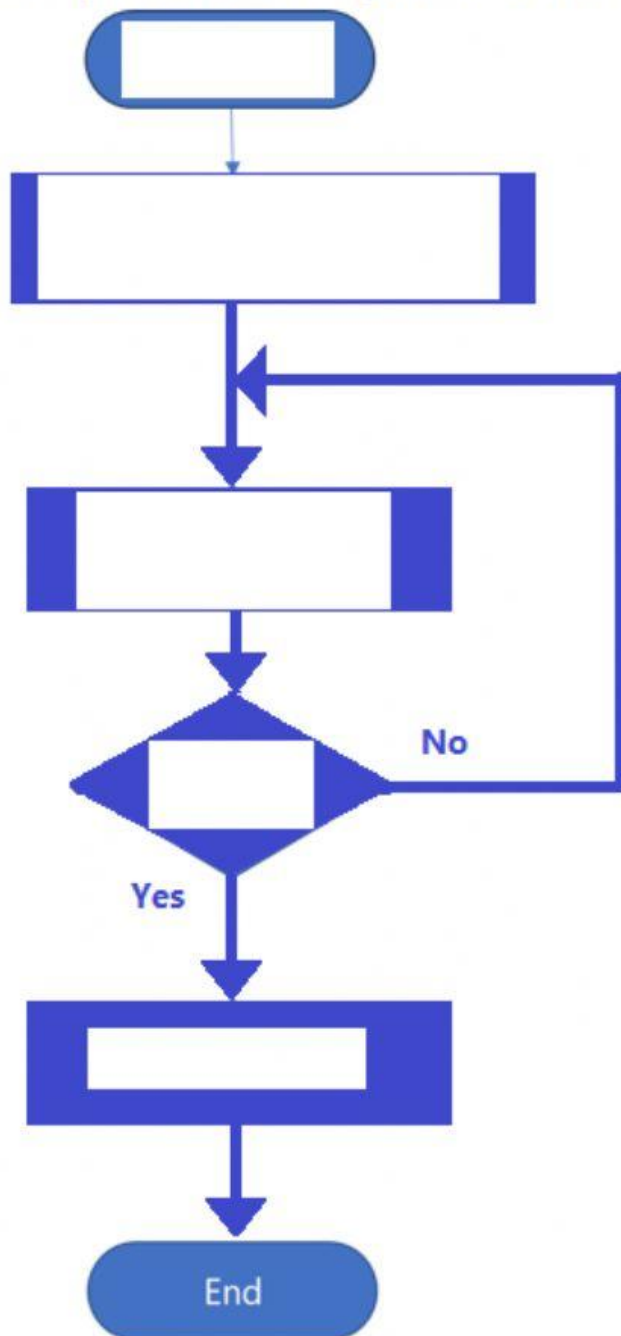


Create a simple flowchart algorithm to move a robot from point A to point B.



Set the pins connected to the servomotors.

**Start**

Move the robot forwards

**Stop the Robot**

is point B reached?