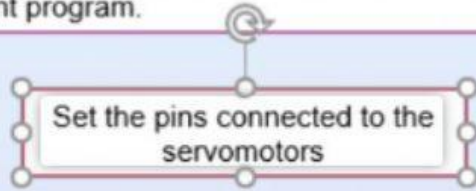


ACTIVITY : FLOWCHART

Create a flowchart algorithm for the basic robot movement program.



Move the robot forwards

Wait for 2 seconds

Stop the robot

