

calibrate the servomotors:

- connect the servomotors to pins 3 and 6.
- create and upload a servomotor program with a stop command.
- use a screwdriver to rotate the screw on the bottom of each servomotor until it stops moving.

Here is an example of a servomotor program with a stop instruction.

Arduino run first:

Arduino loop forever:

Stop robot

Setup
Version 1

Configure drive robot: left motor pin# D3 , right motor pin# D6