

create a program which will do the following:

- connect the servomotors to pins 3 and 6.
- Set the left motor speed to "low"
- Wait 2 seconds
- Set the left motor speed to "high"
- Wait 2 seconds
- Set the right motor speed to "low"
- Wait 2 seconds
- Set the right motor speed to "high"
- Wait 2 seconds

Arduino run first:

Arduino loop forever:

Configure drive robot: left motor pin# , right motor pin#

Drive robot , speed to

wait milliseconds

Drive robot , speed to

wait milliseconds

Drive robot , speed to

wait milliseconds

Drive robot , speed to

wait milliseconds