Informatic

Name_____

ID _____ **Faculty**_____

Part A: Listen the pronunciation and write the word you understand

-ˈdeɪtə _____

-ˈvaɪərəs _____

-kəmˈpjuːtə _____

-geɪmz _____

-ˈkiːbɔːd _____

-maʊs _____

-ˈɪntəˌnɛt _____

-kəˈnɛkʃən _____

-rəʊˈbɒtɪks _____

-jɑːˈhuː _____

Part B: Phrases transcribed into English spelling: Choose the correct answer

1-ɪt ɪz ə ˈsɪstɪm ɒv ˈnɛtwɜːks ˌɪntəkəˈnɛktɪd baɪ ˈdɪfrənt ˈprəʊtəkɒlz ðæt ˈɒfəz ə waɪd reɪnʤ

It is a system of networks interconnected by different protocols that offers a wide range of services and resources, such as access to hypertext files via the Web.
The Internet is an anglicism formed from the abbreviation of the term International Network of Computer.

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2-ˈvaɪərəsɪz ˈjuːʒʊəli rɪˈpleɪs ˈɛksɪkjuːtəbl faɪlz wɪð ˈʌðə faɪlz ɪnˈfɛktɪd

Computer: A computer virus is software that is intended to alter the normal operation of any type of computing device, without the user's permission or knowledge primarily to achieve malicious purposes on the device.
Viruses usually replace executable files with other files infected with the virus code.

3- ɪt dɪˈtɛkts ðeə ˈrɛlətɪv ˈmuːvmənt ɪn tuː dɪˈmɛnʃənz ɒn ðə flæt ˈsɜːfɪs.

The mouse: is a pointing device used to facilitate the operation of a graphical environment on a computer. It is usually made of plastic, and is used with one hand.
It detects its relative movement in two dimensions by the flat surface on which it rests, usually reflected by a pointer, cursor or arrow on the monitor.

4- ðə kəmˈpjuːtə rɪˈlaɪd ɒn ə ˈsɪəriːz ɒv ˈswɪʧɪz tuː ˈɪnpʊt ˈdeɪtə

The first personal computer

In 1975, Ed Roberts coined the term "personal computer" when he introduced the Altair 8800. Although the first personal computer is considered by many to be the KENBAK-1. It was first introduced for $750 in 1971.
The computer relied on a series of switches to input data and output data by turning a series of lights on and off.

5- bɪˈheɪvjər ɒv ə ˈrəʊbɒt kənˈdɪʃən ɪts ˌsjuːtəˈbɪlɪti.

APPLICATION OF ROBOTICS

Robotics today encompasses a wide range of devices with very diverse physical and functional traits associated with their particular mechanical structure, their operational characteristics and the field of application for which they are designed. It is important to emphasize that all these factors are closely related, in such a way that the configuration and behavior of a robot condition its suitability for a given field of applications.

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