# ACTIVITY : FLOWCHART

Create a flowchart algorithm for the basic robot movement program.

Set the pins connected to the servomotors
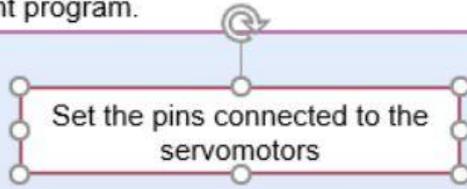
Move the robot forwards

Wait for 2 seconds

Stop the robot

Start

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End