ACTIVITY : FLOWCHART

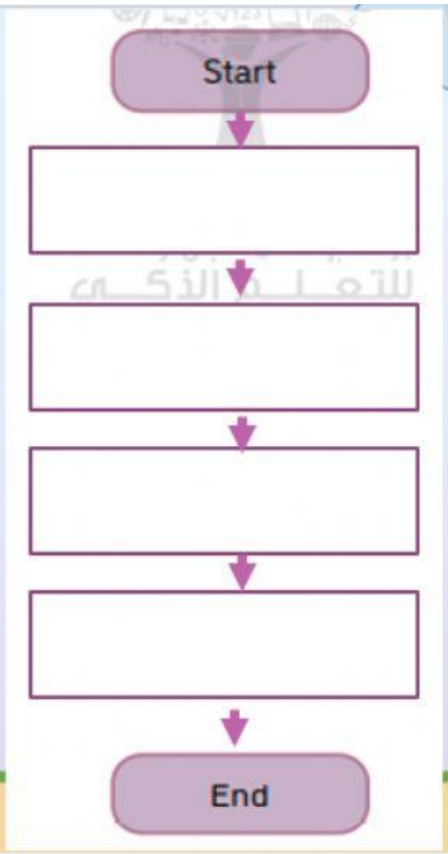
Create a flowchart algorithm for the basic robot movement program.

Set the pins connected to the servomotors

Move the robot forwards

Wait for 2 seconds

Stop the robot



LIVEWORKSHEETS