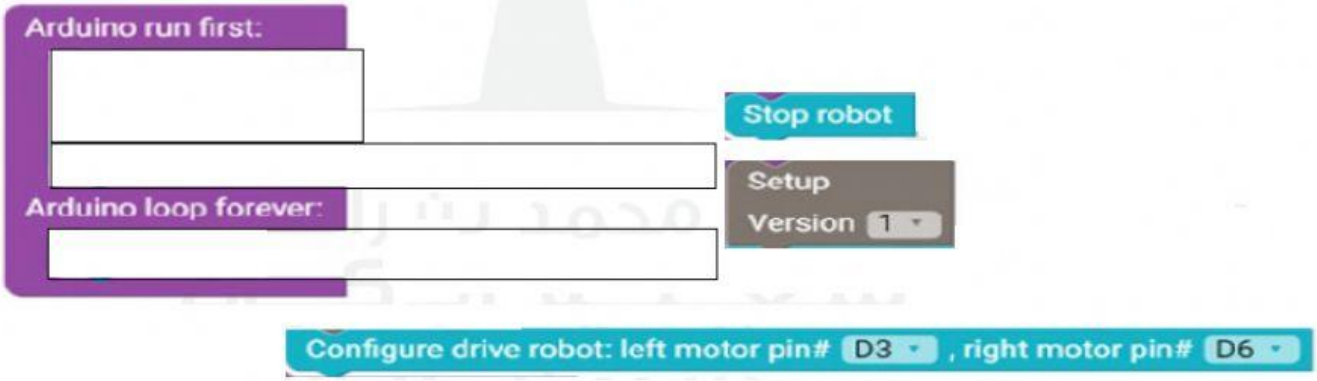
calibrate the servomotors:

- connect the servomotors to pins 3 and 6.
- create and upload a servomotor program with a stop command.
- use a screwdriver to rotate the screw on the bottom of each servomotor until it stops moving.

Here is an example of a servomotor program with a stop instruction.



LIVEWORKSHEETS