

Informatic

Name _____

ID _____

Faculty _____

Part A: Listen the pronunciation and write the word you understand

- 'dɛrtə _____
- 'vaɪərəs _____
- kəm'pjʊ:tə _____
- geɪmz _____
- 'ki:bɔ:d _____
- maʊs _____
- 'ɪntə,net _____
- kə'nekʃən _____
- rəʊ'bɒtɪks _____
- jɑ:'hu: _____



Part B: Phrases transcribed into English spelling: Choose the correct answer

1-ɪt ɪz ə 'sɪstɪm ɒv 'netwɜ:k ɪntəkə'nektɪd baɪ 'dɪfrənt 'prɒtəkɒlz ðæt 'ɒfəz ə waɪd reɪndʒ

It is a system of networks interconnected by different protocols that offers a wide range of services and resources, such as access to hypertext files via the Web.
The Internet is an anglicism formed from the abbreviation of the term International Network of Computer.

2- 'vaɪərəʊsɪz 'ju:ʒəli rɪ'pleɪs 'eksɪkjʊ:təbl faɪlz wɪð 'lðə faɪlz ɪn'fektɪd

Computer: A computer virus is software that is intended to alter the normal operation of any type of computing device, without the user's permission or knowledge primarily to achieve malicious purposes on the device. Viruses usually replace executable files with other files infected with the virus code.

3- ɪt dɪ'tekts ðəə 'relatɪv 'mu:vmənt ɪn tu: dɪ'menʃənz ɒn ðə flæt 'sɜ:fɪs.

The mouse: is a pointing device used to facilitate the operation of a graphical environment on a computer. It is usually made of plastic, and is used with one hand. It detects its relative movement in two dimensions by the flat surface on which it rests, usually reflected by a pointer, cursor or arrow on the monitor.

4- ðə kəm'pjʊ:tə rɪ'laid ɒn ə 'sɪəri:z ɒv 'swɪtʃɪz tu: 'ɪnpʊt 'deɪtə

The first personal computer

In 1975, Ed Roberts coined the term "personal computer" when he introduced the Altair 8800. Although the first personal computer is considered by many to be the KENBAK-1. It was first introduced for \$750 in 1971. The computer relied on a series of switches to input data and output data by turning a series of lights on and off.

5- bɪ'heɪvjər ɒv ə 'rəʊbɒt kən'dɪʃən ɪts ,sju:tə'bɪlɪti.

APPLICATION OF ROBOTICS

Robotics today encompasses a wide range of devices with very diverse physical and functional traits associated with their particular mechanical structure, their operational characteristics and the field of application for which they are designed. It is important to emphasize that all these factors are closely related, in such a way that the configuration and behavior of a robot condition its suitability for a given field of applications.

